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Weekly Report 9

I connected my LCD screen this week so I can start calibrating the sonar sensors and write the full obstacle avoidance code.

The custom boards I designed will be arriving sometime today so I'll start building them tomorrow. I designed two boards - one for line following and one for optoisolation with the motor drivers and an analog mux for my sonar sensors. I also included a D-15 game port for my joystick which uses another two A/D channels.

Otherwise, I haven't done much this week. I'd like to put in some work over the break if I can get in the lab.